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2015 年 4 月

FSBB30CH60D

Motion SPM® 3 系列

特性

- 通过 UL 第 E209204 号认证 (UL1557)
- 600 V - 30 A 三相 IGBT 逆变器, 包含栅极驱动和保护的控制 IC
- 低损耗、短路额定的 IGBT
- 采用 DBC (Al_2O_3) 基板实现非常低的热阻
- 内置自举二极管和专用的 Vs 引脚以简化印刷电路板布局
- 低端 IGBT 的独立发射极开路引脚用于三相电流感测
- 单接地电源供电
- LVIC 内嵌温度感测功能, 用于监控温度
- 绝缘等级: 2500 V_{rms} / 分钟

应用

- 运动控制 — 家用设备 / 工业电机

相关资料

- [AN-9085 - Motion SPM® 3 Ver.5 Series Users Guide](#)
- [AN-9086 - SPM 3 Package Mounting Guide](#)
- [AN-9087 - Motion SPM® 3 Ver.5 Series Thermal Performance Information](#)

概述

FSBB30CH60D 是一款先进的 Motion SPM® 3 模块, 为交流感应、无刷直流电机和 PMSM 电机提供非常全面的高性能逆变器输出平台。该型号内建 IGBT 优化栅极驱动, 最大限度降低电磁辐射和损耗, 同时提供多种自带保护功能, 包括欠压闭锁、过流关断、驱动芯片热监控和故障报告。内置的高速 HVIC 只需要一个单电源电压, 将逻辑电平栅极输入转化为适合驱动模块内部 IGBT 的高电压, 高电流驱动信号。独立的 IGBT 负端在每个相位均有效, 可支持大量不同种类的控制算法。

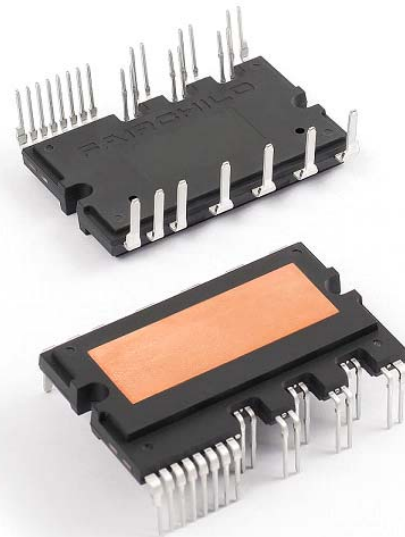


图 1. 封装概览

封装标识与订购信息

| 器件 | 器件标识 | 封装 | 包装类型 | 数量 |
|-------------|-------------|-----------|------|----|
| FSBB30CH60D | FSBB30CH60D | SPMPA-027 | Rail | 10 |

集成的功率功能

- 600 V - 30 A IGBT 逆变器，适用于三相 DC / AC 功率转换（请参阅图 3）

集成的驱动、保护和系统控制功能

- 对于逆变器高端 IGBT：栅极驱动电路、高压隔离的高速电平转换
控制电路欠压锁定保护 (UVLO)
注：可用自举电路示例如图 5 和图 15 所示。
- 对于逆变器低端 IGBT：栅极驱动电路、短路保护 (SCP)
控制电源欠压锁定保护 (UVLO)
- 故障信号：对应 UVLO（低端电源）和短路故障
- 输入接口：高电平有效接口，可用于 3.3 / 5 V 逻辑电平，施密特触发脉冲输入

引脚布局

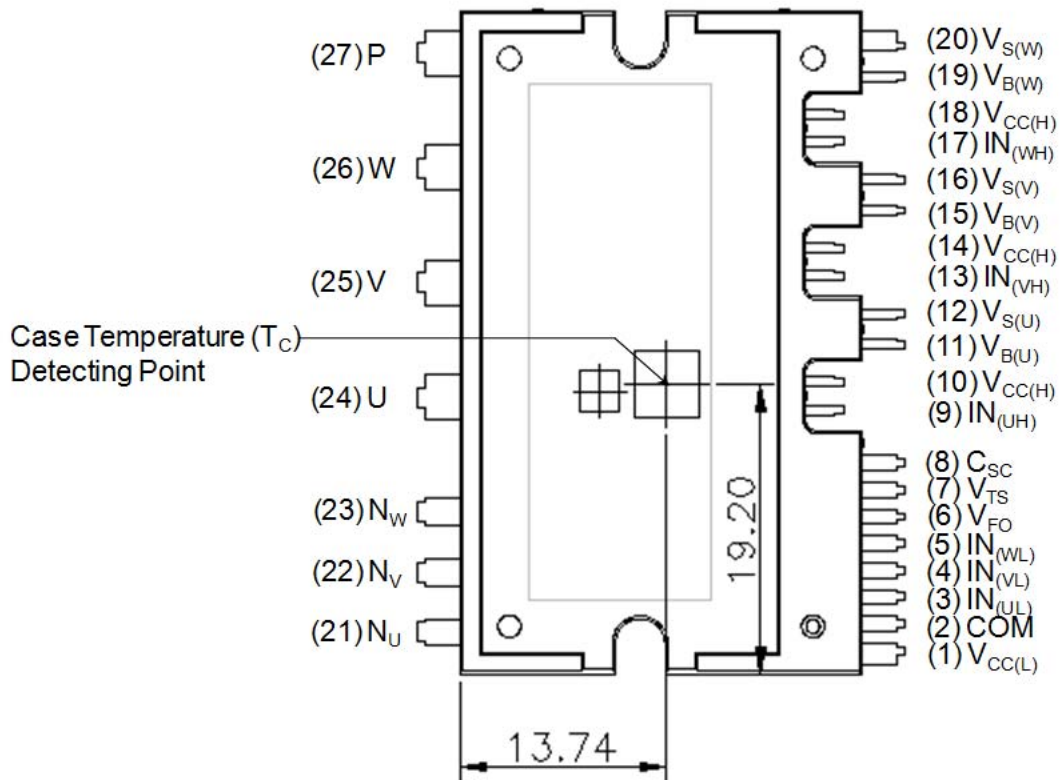


图 2. 俯视图



引脚描述

| 引脚号 | 引脚名 | 引脚描述 |
|-----|--------------------|---------------------|
| 1 | V _{CC(L)} | IC 和 IGBT 驱动的低端公共偏压 |
| 2 | COM | 公共电源接地 |
| 3 | IN _(UL) | 低端 U 相的信号输入 |
| 4 | IN _(VL) | 低端 V 相的信号输入 |
| 5 | IN _(WL) | 低端 W 相的信号输入 |
| 6 | V _{FO} | 故障输出 |
| 7 | V _{TS} | LVIC 温度感测电压输出 |
| 8 | C _{SC} | 短路电流感测输入电容（低通滤波器） |
| 9 | IN _(UH) | 高端 U 相的信号输入 |
| 10 | V _{CC(H)} | IC 和 IGBT 驱动的高端公共偏压 |
| 11 | V _{B(U)} | U 相 IGBT 驱动的高端偏压 |
| 12 | V _{S(U)} | U 相 IGBT 驱动的高端偏压接地 |
| 13 | IN _(VH) | 高端 V 相的信号输入 |
| 14 | V _{CC(H)} | IC 和 IGBT 驱动的高端公共偏压 |
| 15 | V _{B(V)} | V 相 IGBT 驱动的高端偏压 |
| 16 | V _{S(V)} | V 相 IGBT 驱动的高端偏压接地 |
| 17 | IN _(WH) | 高端 W 相的信号输入 |
| 18 | V _{CC(H)} | IC 和 IGBT 驱动的高端公共偏压 |
| 19 | V _{B(W)} | W 相 IGBT 驱动的高端偏压 |
| 20 | V _{S(W)} | W 相 IGBT 驱动的高端偏压接地 |
| 21 | N _U | U 相的直流输入负端 |
| 22 | N _V | V 相的直流输入负端 |
| 23 | N _W | W 相的直流输入负端 |
| 24 | U | U 相输出 |
| 25 | V | V 相输出 |
| 26 | W | W 相输出 |
| 27 | P | 直流输入正端 |



内部等效电路与输入 / 输出引脚

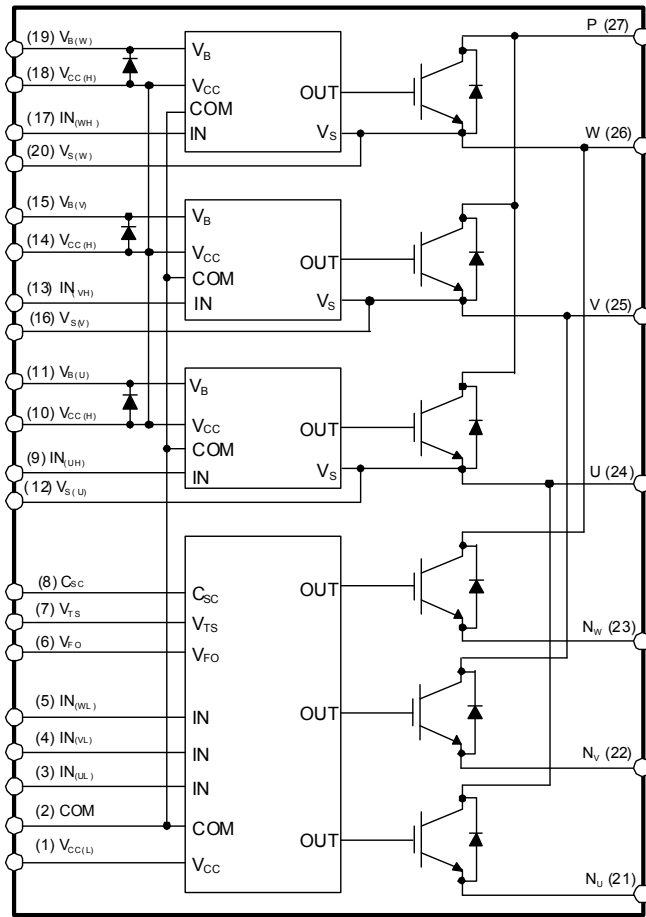


图 3. 内部框图

注:

1. 逆变器的低端由三个 IGBT 及相应的续流二极管和一个控制 IC 组成。具有栅极驱动和保护功能。
2. 逆变器的功率端由逆变器的四个直流母线输入端和三个输出端组成。
3. 逆变器高端由三个 IGBT 组成，每个 IGBT 包括续流二极管和三个驱动 IC。



绝对最大额定值 ($T_J = 25^\circ\text{C}$, 除非另有说明。)**逆变器部分**

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|---------------|---------------------|---|-----------|------------------|
| V_{PN} | 电源电压 | 施加在 P - N_U , N_V , N_W 之间 | 450 | V |
| V_{PN} (浪涌) | 电源电压 (浪涌) | 施加在 P - N_U , N_V , N_W 之间 | 500 | V |
| V_{CES} | 集电极 — 发射极之间电压 | | 600 | V |
| $\pm I_C$ | 单个 IGBT 的集电极电流 | $T_C = 25^\circ\text{C}$, $T_J \leq 150^\circ\text{C}$ (注 4) | 30 | A |
| $\pm I_{CP}$ | 单个 IGBT 的集电极电流 (峰值) | $T_C = 25^\circ\text{C}$, $T_J \leq 150^\circ\text{C}$, 脉冲宽度小于 1 ms (注 4) | 60 | A |
| P_C | 集电极功耗 | $T_C = 25^\circ\text{C}$ per One Chip (注 4) | 113 | W |
| T_J | 工作结温 | | -40 ~ 150 | $^\circ\text{C}$ |

控制部分

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|----------|----------|--|---------------------|----|
| V_{CC} | 控制电源电压 | 施加在 $V_{CC(H)}$, $V_{CC(L)}$ - COM 之间 | 20 | V |
| V_{BS} | 高端控制偏压 | 施加在 $V_{B(U)} - V_{S(U)}$, $V_{B(V)} - V_{S(V)}$, $V_{B(W)} - V_{S(W)}$ | 20 | V |
| V_{IN} | 输入信号电压 | 施加在 $IN_{(UH)}$, $IN_{(VH)}$, $IN_{(WH)}$, $IN_{(UL)}$, $IN_{(VL)}$, $IN_{(WL)}$ - COM 之间 | -0.3 ~ $V_{CC}+0.3$ | V |
| V_{FO} | 故障输出电源电压 | 施加在 V_{FO} - COM 之间 | -0.3 ~ $V_{CC}+0.3$ | V |
| I_{FO} | 故障输出电流 | V_{FO} 引脚处的灌电流 | 2 | mA |
| V_{SC} | 电流感测输入电压 | 施加在 C_{SC} - COM 之间 | -0.3 ~ $V_{CC}+0.3$ | V |

自举二极管部分

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|-----------|-----------|---|-----------|------------------|
| V_{RRM} | 最大重复反向电压 | | 600 | V |
| I_F | 正向电流 | $T_C = 25^\circ\text{C}$, $T_J \leq 150^\circ\text{C}$ (注 4) | 0.5 | A |
| I_{FP} | 正向电流 (峰值) | $T_C = 25^\circ\text{C}$, $T_J \leq 150^\circ\text{C}$, 脉冲宽度小于 1 ms (注 4) | 2.0 | A |
| T_J | 工作结温 | | -40 ~ 150 | $^\circ\text{C}$ |

整个系统

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|----------------|---------------------|--|-----------|------------------|
| $V_{PN(Prot)}$ | 自我保护限制电源电压 (短路保护能力) | $V_{CC} = V_{BS} = 13.5 \sim 16.5 \text{ V}$, $T_J = 150^\circ\text{C}$, 非重复性, $< 2 \mu\text{s}$ | 400 | V |
| T_C | 模块壳体工作温度 | 见图 2 | -40 ~ 125 | $^\circ\text{C}$ |
| T_{STG} | 存储温度 | | -40 ~ 125 | $^\circ\text{C}$ |
| V_{ISO} | 绝缘电压 | 60 Hz, 正弦波形, 1 分钟, 连接陶瓷基板到引脚 | 2500 | V_{rms} |

热阻

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 |
|----------------|------------------|------------------------|-----|-----|------|---------------------------|
| $R_{th(j-c)Q}$ | 结点 — 壳体的热阻 (注 5) | 逆变器 IGBT 部分 (每 1/6 模块) | - | - | 1.10 | $^\circ\text{C}/\text{W}$ |
| $R_{th(j-c)F}$ | | 逆变器 FWD 部分 (每 1/6 模块) | - | - | 2.10 | $^\circ\text{C}/\text{W}$ |

注:

4. 这些值获取了考虑到设计因素的计算结果。
5. 关于壳体温度 (T_C) 的测量点, 请参阅图 2。

电气特性 ($T_J = 25^\circ\text{C}$, 除非另有说明。)

逆变器部分

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 |
|---------------|----------------|--|------|------|------|---------------|
| $V_{CE(SAT)}$ | 集电极 — 发射极间饱和电压 | $V_{CC} = V_{BS} = 15\text{ V}$ $V_{IN} = 5\text{ V}$ | - | 1.50 | 2.10 | V |
| V_F | FWD 正向电压 | $V_{IN} = 0\text{ V}$ $I_F = 30\text{ A}, T_J = 25^\circ\text{C}$ | - | 1.80 | 2.40 | V |
| HS | t_{ON} | 开关时间 $V_{PN} = 300\text{ V}, V_{CC} = 15\text{ V}, I_C = 30\text{ A}$ $T_J = 25^\circ\text{C}$ $V_{IN} = 0\text{ V} \leftrightarrow 5\text{ V}$, 电感负载 见图 5 (注 6) | 0.50 | 0.90 | 1.40 | μs |
| | $t_{C(ON)}$ | | - | 0.25 | 0.55 | μs |
| | t_{OFF} | | - | 0.90 | 1.40 | μs |
| | $t_{C(OFF)}$ | | - | 0.10 | 0.40 | μs |
| | t_{rr} | | - | 0.10 | - | μs |
| LS | t_{ON} | $V_{PN} = 300\text{ V}, V_{CC} = 15\text{ V}, I_C = 30\text{ A}$ $T_J = 25^\circ\text{C}$ $V_{IN} = 0\text{ V} \leftrightarrow 5\text{ V}$, 电感负载 见图 5 (注 6) | 0.40 | 0.80 | 1.30 | μs |
| | $t_{C(ON)}$ | | - | 0.25 | 0.55 | μs |
| | t_{OFF} | | - | 0.90 | 1.40 | μs |
| | $t_{C(OFF)}$ | | - | 0.15 | 0.45 | μs |
| | t_{rr} | | - | 0.10 | - | μs |
| I_{CES} | 集电极 — 发射极间漏电流 | $V_{CE} = V_{CES}$ | - | - | 5 | mA |

注:

6. t_{ON} 和 t_{OFF} 包括模块内部驱动 IC 的传输延迟时间。 $t_{C(ON)}$ 和 $t_{C(OFF)}$ 指在内部给定的栅极驱动条件下, IGBT 本身的开关时间。详细信息, 请参见图 4。

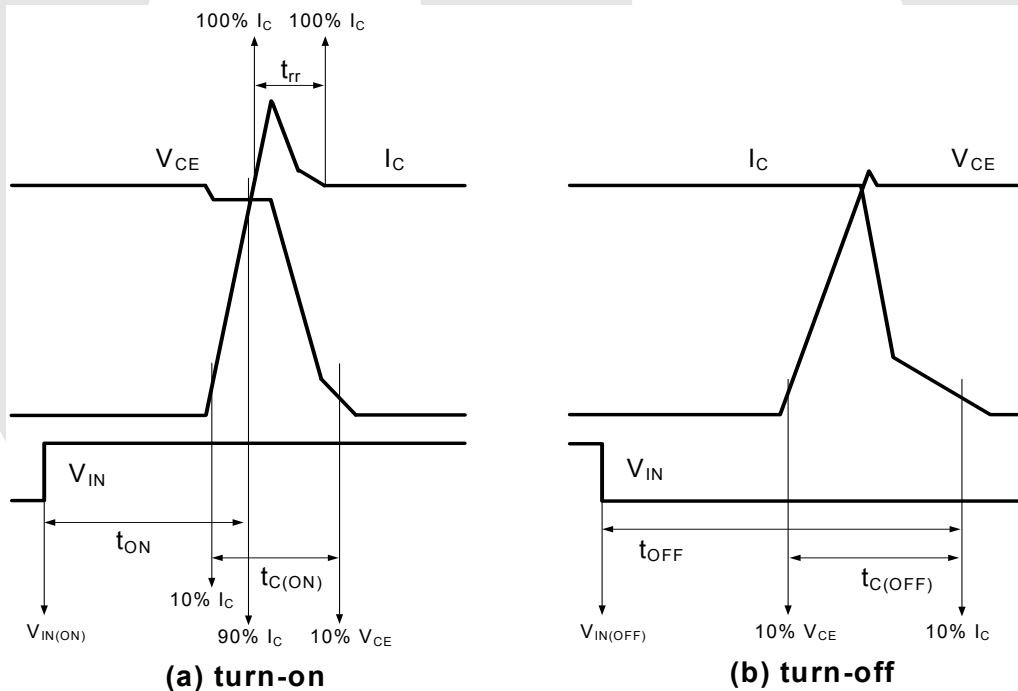


图 4. 开关时间的定义

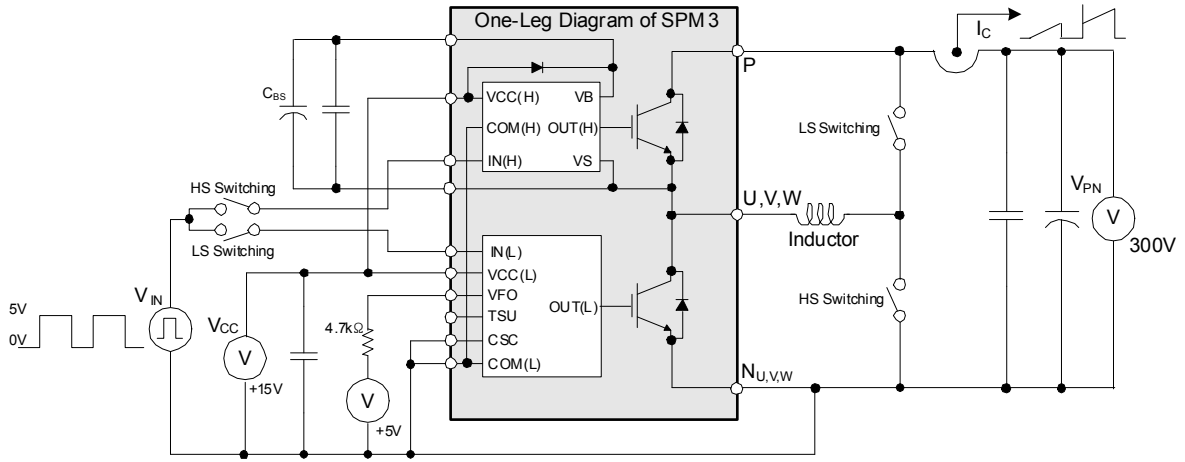


图 5. 开关测试电路实例

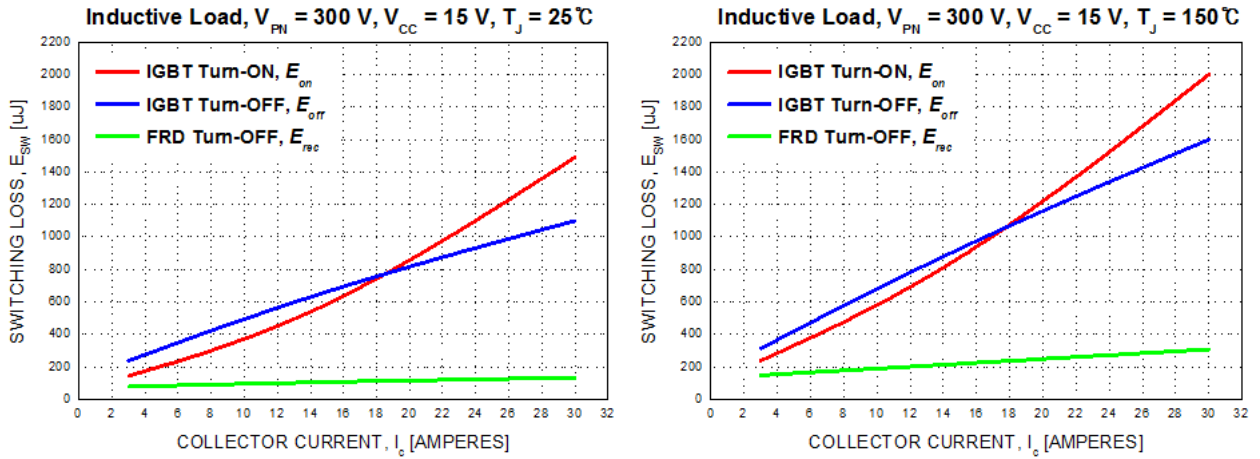


图 6. 开关损耗特性

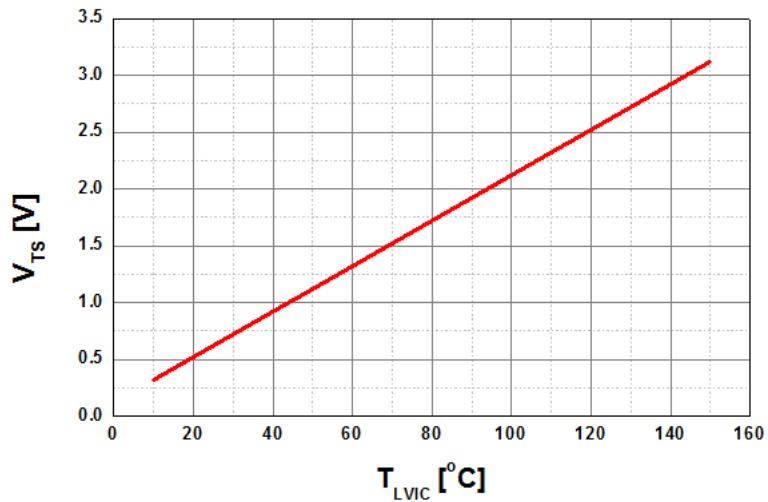


图 7. V_{TS} 的温度曲线 (典型值)

自举二极管部分

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 |
|----------|--------|---|-----|-----|-----|----|
| V_F | 正向电压 | $I_F = 0.1 \text{ A}$, $T_J = 25^\circ\text{C}$ | - | 2.5 | - | V |
| t_{rr} | 反向恢复时间 | $I_F = 0.1 \text{ A}$, $di_F / dt = 50 \text{ A} / \mu\text{s}$, $T_J = 25^\circ\text{C}$ | - | 80 | - | ns |

控制部分

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 | |
|---------------|-----------------|--|---|------|------|------|----|
| I_{QCCH} | V_{CC} 静态电源电流 | $V_{CC(H)} = 15 \text{ V}$, $I_{N(UH, VH, WH)} = 0 \text{ V}$ | $V_{CC(H)} - \text{COM}$ | - | - | 0.50 | mA |
| I_{QCCL} | | $V_{CC(L)} = 15 \text{ V}$, $I_{N(UL, VL, WL)} = 0 \text{ V}$ | $V_{CC(L)} - \text{COM}$ | - | - | 6.00 | mA |
| I_{PCCH} | V_{CC} 电源电流 | $V_{CC(H)} = 15 \text{ V}$, $f_{PWM} = 20 \text{ kHz}$, 占空比 = 50%, 施加于高端的一个 PWM 信号输入 | $V_{CC(H)} - \text{COM}$ | - | - | 0.50 | mA |
| I_{PCCL} | | $V_{CC(L)} = 15 \text{ V}$, $f_{PWM} = 20 \text{ kHz}$, 占空比 = 50%, 施加于低端的一个 PWM 信号输入 | $V_{CC(L)} - \text{COM}$ | - | - | 10.0 | mA |
| I_{QBS} | V_{BS} 静态电源电流 | $V_{BS} = 15 \text{ V}$, $I_{N(UH, VH, WH)} = 0 \text{ V}$ | $V_{B(U)} - V_{S(U)}$, $V_{B(V)} - V_{S(V)}$, $V_{B(W)} - V_{S(W)}$ | - | - | 0.30 | mA |
| I_{PBS} | V_{BS} 工作电源电流 | $V_{CC} = V_{BS} = 15 \text{ V}$, $f_{PWM} = 20 \text{ kHz}$, 占空比 = 50%, 施加于高端的一个 PWM 信号输入 | $V_{B(U)} - V_{S(U)}$, $V_{B(V)} - V_{S(V)}$, $V_{B(W)} - V_{S(W)}$ | - | - | 4.50 | mA |
| V_{FOH} | 故障输出电压 | $V_{CC} = 15 \text{ V}$, $V_{SC} = 0 \text{ V}$, V_{FO} 电路: 4.7 kΩ 至 5 V Pull-up | | 4.5 | - | - | V |
| V_{FOL} | | $V_{CC} = 15 \text{ V}$, $V_{SC} = 1 \text{ V}$, V_{FO} 电路: 4.7 kΩ 至 5 V Pull-up | | - | - | 0.5 | V |
| $V_{SC(ref)}$ | 短路触发电平 | $V_{CC} = 15 \text{ V}$ (注 7) | $C_{SC} - \text{COM}_{(L)}$ | 0.45 | 0.50 | 0.55 | V |
| UV_{CCD} | 电源电路欠压保护 | 检测电平 | | 9.8 | - | 13.3 | V |
| UV_{CCR} | | 复位电平 | | 10.3 | - | 13.8 | V |
| UV_{BSD} | | 检测电平 | | 9.0 | - | 12.5 | V |
| UV_{BSR} | | 复位电平 | | 9.5 | - | 13.0 | V |
| t_{FOD} | 故障输出脉宽 | | | 50 | - | - | μs |
| V_{TS} | LVIC 温度感应电压输出 | $V_{CC(L)} = 15 \text{ V}$, $T_{LVIC} = 25^\circ\text{C}$ (注 8) 见图 7 | | 540 | 640 | 740 | mV |
| $V_{IN(ON)}$ | 导通阈值电压 | 施加在 $I_{N(UH, VH, WH)} - \text{COM}$, $I_{N(UL, VL, WL)} - \text{COM}$ 之间 | | - | - | 2.6 | V |
| $V_{IN(OFF)}$ | 关断阈值电压 | | | 0.8 | - | - | V |

注:

7. 短路电流保护仅作用于低端。

8. T_{LVIC} 是 LVIC 自身的温度。 V_{TS} 只能用作 LVIC 的温度感测, 但不能自动关闭 IGBTs。

推荐工作条件

| 符号 | 参数 | 工作条件 | 数值 | | | 单位 |
|--------------------------------|-------------|---|------|-----|------|------------------|
| | | | 最小值 | 典型值 | 最大值 | |
| V_{PN} | 电源电压 | 施加在 P - N_U , N_V , N_W 之间 | - | 300 | 400 | V |
| V_{CC} | 控制电源电压 | 施加在 $V_{CC(UH, VH, WH)} - COM$, $V_{CC(L)} - COM$ 之间 | 14.0 | 15 | 16.5 | V |
| V_{BS} | 高端偏压 | 施加在 $V_{B(U)} - V_{S(U)}$, $V_{B(V)} - V_{S(V)}$, $V_{B(W)} - V_{S(W)}$ | 13.0 | 15 | 18.5 | V |
| dV_{CC}/dt , dV_{BS}/dt | 控制电源的波动 | | -1 | - | 1 | V/ μ s |
| t_{dead} | 防止桥臂直通的死区时间 | 适用于每个输入信号 | 1.0 | - | - | μ s |
| f_{PWM} | PWM 输入信号 | $-40^\circ\text{C} \leq T_C \leq 125^\circ\text{C}$, $-40^\circ\text{C} \leq T_J \leq 150^\circ\text{C}$ | - | - | 20 | kHz |
| V_{SEN} | 电流感测的电压 | 施加在 N_U , N_V , $N_W - COM$ 之间 (包括浪涌电压) | -5 | - | 5 | V |
| $PW_{IN(ON)}$ | 最小输入脉宽 | $V_{CC} = V_{BS} = 15\text{ V}$, $I_C \leq 60\text{ A}$, 线路电感在 N_U, V, W 和直流母线 N < 之间为 10nH (注 9) | 2.0 | - | - | μ s |
| $PW_{IN(OFF)}$ | | | 2.0 | - | - | |
| T_J | 结温 | | -40 | - | 150 | $^\circ\text{C}$ |

注:

9. 此产品可能不会响应, 若输入脉宽值低于最低推荐值。

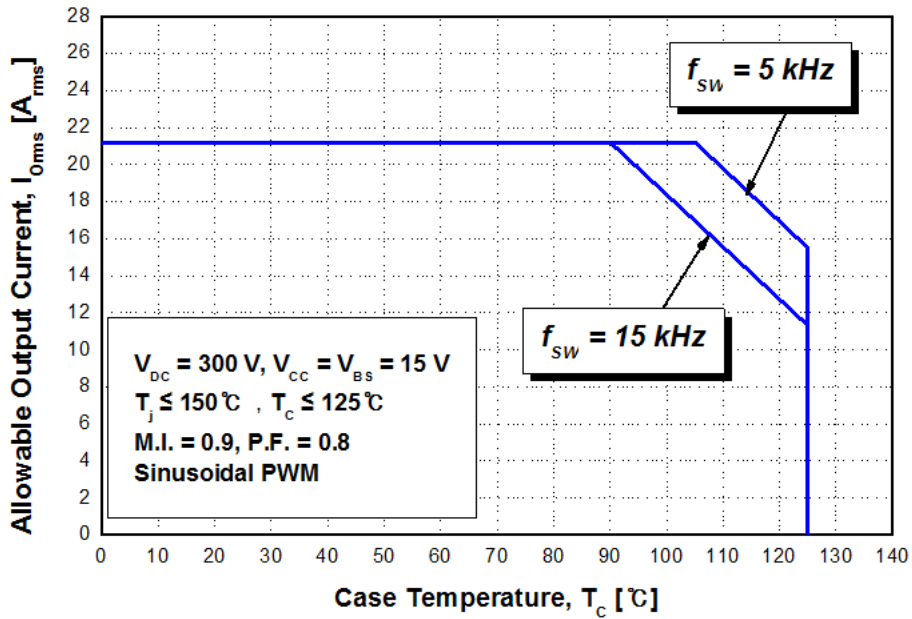


图 8. 允许最大输出电流

注:

10. 这个允许输出电流值是该产品安全工作时的参考值。考虑到实际应用和工作条件, 它可能会改变。

机械特性和额定值

| 参数 | 工作条件 | | 极限值 | | | 单位 |
|--------|------------------|--------------|-----|-----|------|-------|
| | | | 最小值 | 典型值 | 最大值 | |
| 器件平面度 | 见图 9 | | 0 | - | +150 | μm |
| 安装扭矩 | 安装螺钉: M3 | 建议 0.7 N·m | 0.6 | 0.7 | 0.8 | N·m |
| | 见图 10 | 建议 7.1 kg·cm | 6.2 | 7.1 | 8.1 | kg·cm |
| 一端拉力强度 | 负载 19.6 N | | 10 | - | - | S |
| 一端弯曲强度 | 负载 9.8 N, 90 度弯曲 | | 2 | - | - | 次 |
| 重量 | | | - | 15 | - | g |

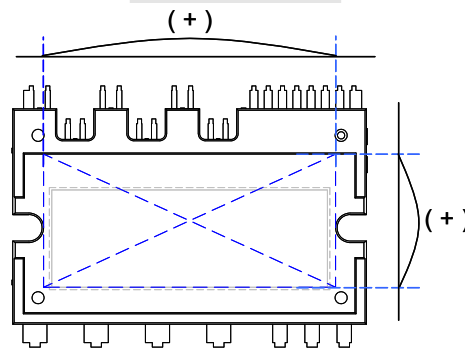


图 9. 平面度测量位置

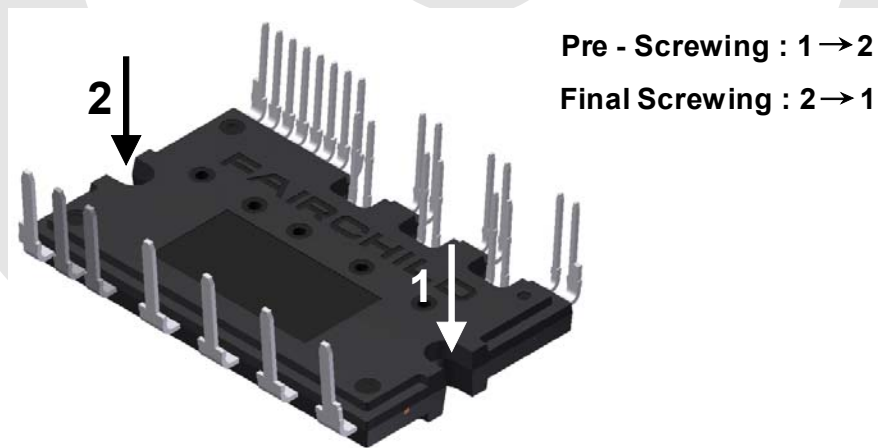


图 10. 安装螺钉时的扭紧顺序

注:

- 11. 安装或扭动螺丝时切勿过分用力。扭力过大会造成 DBC 基底破裂, 产生毛刺并破坏铝质散热片。
- 12. 避免用力不均衡。图 10 显示了安装螺钉时, 推荐的扭紧顺序。安装不平整会破坏封装 DBC 基底。预旋紧扭矩约为最大额定扭矩的 20 ~ 30%。

SPM 保护功能时序图

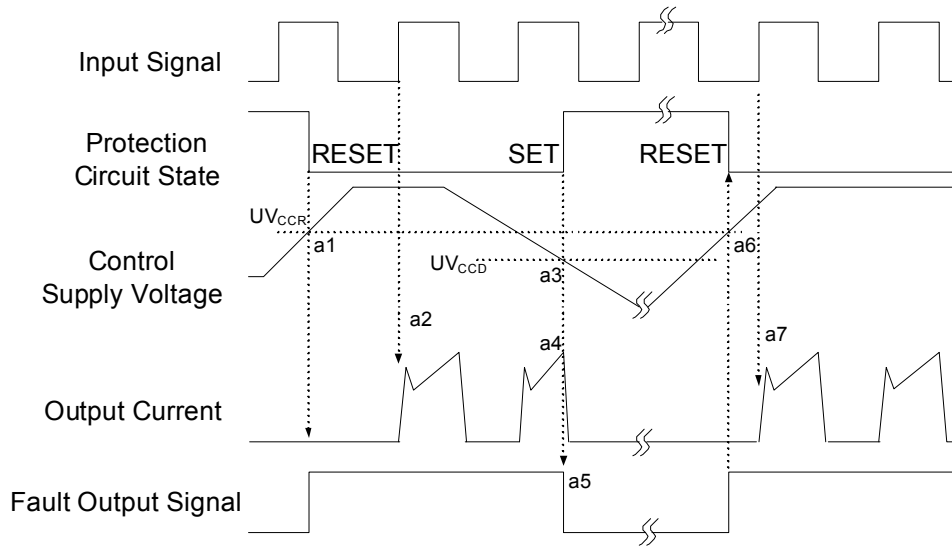


图 11. 欠压保护（低端）

- a1: 控制电源电压上升: 当电压上升到 UV_{CCR} 后, 等到下一个开通信号时, 对应的电路才开始动作。
- a2: 正常工作: IGBT 导通并加载负载电流。
- a3: 欠压检测 (UV_{CCD})。
- a4: 不论控制输入的条件, IGBT 都关断。
- a5: 故障输出工作从一个固定脉冲宽度启动。
- a6: 欠压复位 (UV_{CCR})。
- a7: 正常工作: 当触发下一个低状态到高状态的信号, IGBT 导通并加载负载电流。

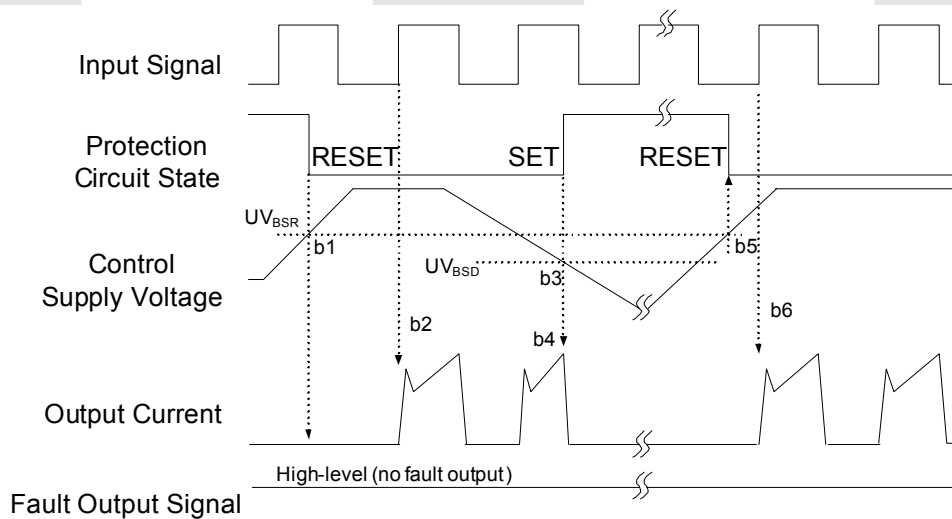


图 12. 欠压保护（高端）

- b1: 控制电源电压上升: 当电压上升到 UV_{BSR} 后, 等到下一个输入信号时, 对应的电路才开始动作。
- b2: 正常工作: IGBT 导通并加载负载电流。
- b3: 欠压检测 (UV_{BSD})。
- b4: 不论控制输入的条件, IGBT 都关闭, 且无故障输出信号。
- b5: 欠压复位 (UV_{BSR})。
- b6: 正常工作: 当触发下一个低状态到高状态的信号, IGBT 导通并加载负载电流。

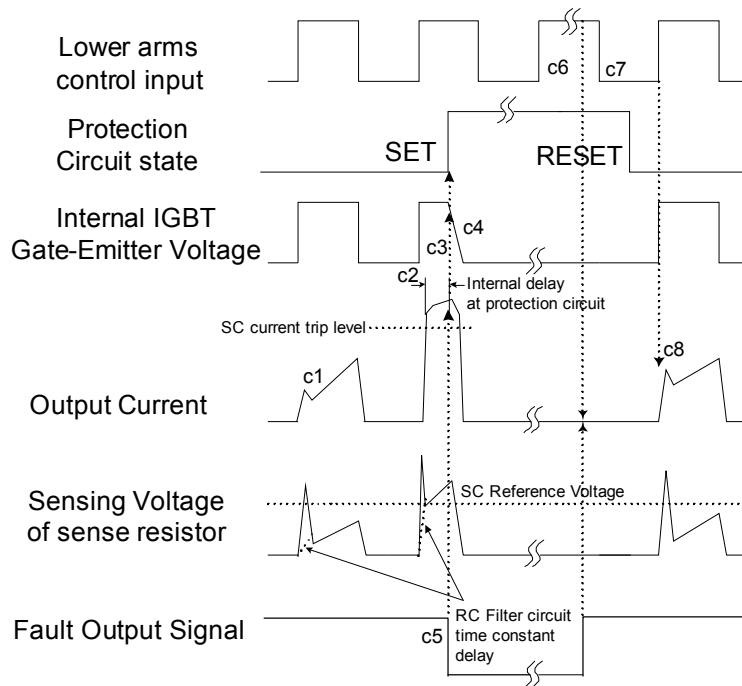


图 13. 短路电流保护（仅适用于低端工作）

（包含外部感测电阻和阻容滤波器连接）

- c1: 正常工作: IGBT 导通并加载负载电流。
- c2: 短路电流检测 (SC 触发)。
- c3: 所有的低端 IGBT 都是栅极硬中断。
- c4: 所有的低端 IGBT 关断。
- c5: 故障输出工作从一个固定脉冲宽度启动。
- c6: 输入高状态: IGBT 导通状态, 但是在故障输出有效的时间内, IGBT 不导通。
- c7: 故障输出工作结束, 但是 IGBT 不导通直到触发下一个低状态到高状态的信号。
- c8: 正常工作: IGBT 导通并加载负载电流。

输入 / 输出接口电路

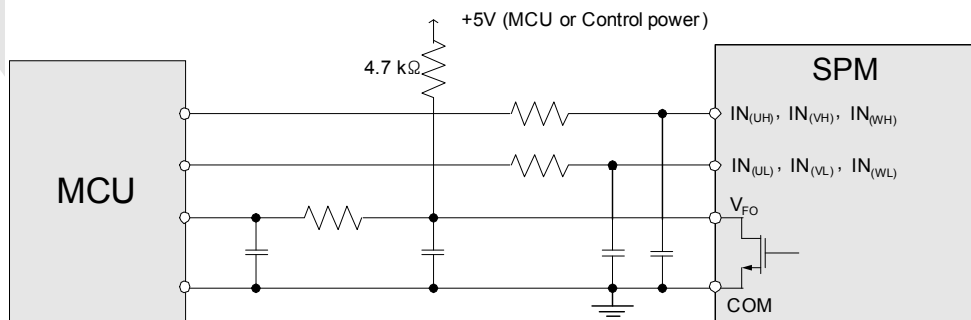
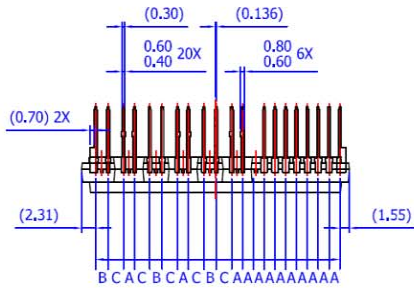


图 14 推荐的 MCU I/O 接口电路

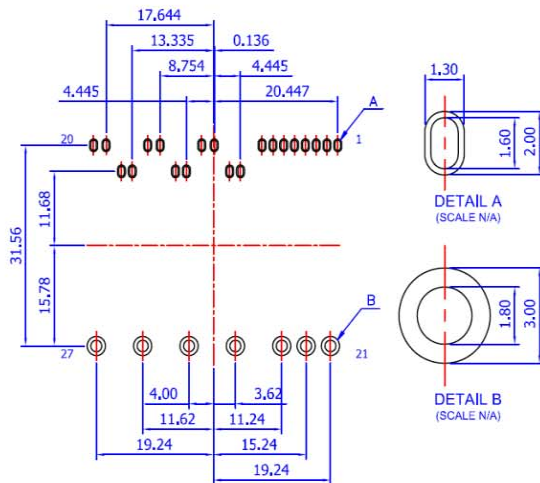
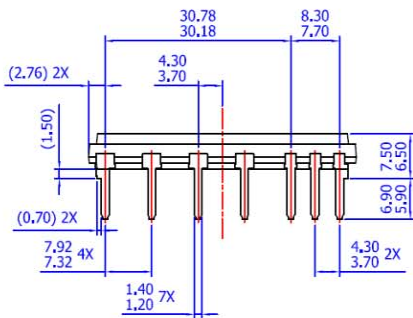
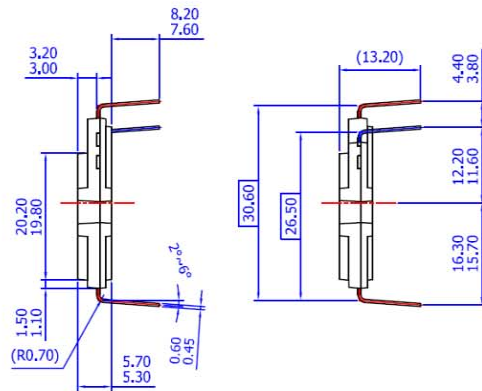
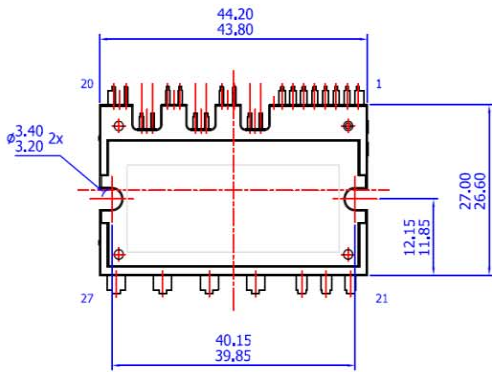
注:

13. 每个输入端的 RC 耦合可能随着应用程序中使用的 PWM 控制方案和应用程序印刷电路板接线抗阻而改变。Motion SPM 3 产品的输入信号部分集成了一个 5 kΩ (典型值) 的下拉电阻。因此, 当使用外部的滤波电阻时, 请注意该信号在输入端的压降。

轮廓封装详图 (FSBB30CH60D)



LEAD PITCH (TOLERANCE : ±0.30)
 A : 1.778
 B : 2.050
 C : 2.531



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